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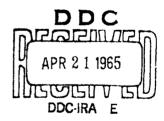
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ATTENUATION OF SHOCKS PRODUCED BY UNLIKE METAL IMPACT

by J. F. Heyda, T. D. Riney, Gen Elec Co.

APRIL 1965



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FOREWORD

This interim report was prepared by the Mechanics Section of the Space Sciences Laboratory of the General Electric Company's Missile and Space Division, under Air Force Contract AF08(635)-3781, "Theoretical Terminal Ballistic Study; Energy Dissipation During Impact." The work was administered under the direction of the Terminal Ballistics Branch, Det. 4, Research and Technology Division, Eglin Air Force Base with Mr. A. G. Bilek and Lt. M. S. Harris as Project Engineers.

The major part of the work during the last six months has been directed towards the improvement of the computer codes for the solution of hypervelocity impact problems. This work is only briefly described here, but the authors wish to acknowledge the contributions of Mr. T. Coffin, and Mrs. J. Goldman in this effort. They are also indebted to Mr. O. A. Winter for assistance in the calculations with the analytical model.

Publication of this report does not constitute Air Force approval of the report's findings or conclusions. It is published only for the exchange and stimulation of ideas.

PUBLICATION REVIEW

This technical report has been reviewed and is approved.

CHARLES E WOOD

Major, USAF

Chief, Ballistics Division

ABSTRACT

An analytical model is presented for determining the peak axial pressure generated at various depths in the target when impacted at hypervelocity by a projectile of similar or dissimilar material. Detailed calculations are given for impact of aluminum, iron, lead and copper into aluminum targets. Available experimental data for impact into aluminum targets are discussed in terms of the theory.

TABLE OF CONTENTS

Section		Page
I.	Introduction	1
II.	Codes and Computer Facilities	3
III.	Review and Formulation of Analytical Model	4
IV.	Extension of the Model to Dissimilar Materials	10
v.	Relation to Other Investigations	15
VI.	Conclusions	19
	References	20

LIST OF SYMBOLS

t	time variable
p	pressure
ρ	density of medium
$ ho_{ m o}$	undisturbed density
x	compression ratio $(= \rho_0/\rho)$
L	radius of cylindrical projectile
ı	length of cylindrical projectile
ī	characteristic length $(=\sqrt[3]{L^2 \iota})$
Ds	diameter of equi-volume sphere
P _c	penetration depth of crater
С	coefficient in penetration formula
v _o	impact velocity
v [*] o	threshold value for energy scaling
E*	threshold energy for energy scaling
() _H	subscript denoting value on the Hugoniot
δ	ratio of projectile density to target density (= $\rho_{\rm p}/\rho_{\rm t}$)
R	distance below target surface of shock
Ř	shock velocity in target
^с н	sound velocity in shocked material
A, K, R _o	parameters in analytical model
R_{1}	position where shock in target first attenuated on axis

SECTION I

INTRODUCTION

In two earlier interim reports [1,2] numerical calculations were presented describing the time dependent flow field produced when a projectile impacts a target at hypervelocity. The calculations were made using a computer code (PICWICK I) for solving the complex system of equations governing a visco-plastic model of the process. The results indicated that in a thick target the depth of penetration, of geometrically similar projectiles of like metal, varies with the impact velocity according to $v^{2/3}$ in the hypervelocity regime. Calculations were also given to show that the crater dimensions are relatively insensitive to the density of homogeneous projectiles of the same basic material. Experimentally observed size effects were discussed in terms of the visco-plastic model and it was concluded that the threshold velocity for energy scaling will depend somewhat on the dimensions of the projectile.

The formula for the depth of penetration based on these results is as follows:

$$P_{c} = C(\rho_{p}/\rho_{t})^{1/3} v_{o}^{2/3} (v_{o} \ge v_{o}^{*}, E_{o} \ge E_{o}^{*}),$$
 (1)

where the constants C, v_0^* and E_0^* must be experimentally determined. E_0^* is a threshold impact energy which reflects the size effect on the threshold impact velocity v_0^* . The material parameters are known from experiment to vary among alloys of nominally the same metal, reflecting strength and strain-rate effects that in the late streets of the flow process determine the final crater dimensions.

Plate targets of finite thickness were also studied in the earlier reports. The forward momentum carried by the spallation bubble from the rear surface of the target was computed for two plate thicknesses. The spatial divergence of the bubble and the corresponding decrease in its projected momentum density was charted. The spread of the loading and the maximum value of the projected momentum density was obtained as a function of the standoff distances. These results are useful in analyzing meteor bumper protection systems. Preliminary calculations were also presented for impact into a target consisting of two spaced plates.

Many important and unresolved questions remain to be studied, especially for finite plate targets and meteor bumper systems. Other problems of practical interest are the penetration effectiveness of projectiles of special geometry. An improved version of the code (PICWICK II) has been under development to treat these problems. Some recently added features are briefly described in the first part of this report. Up to this time, however, computer time has not been available to utilize the improved capability of the code in production runs. The IBM 7094 at Eglin AFB, used for the earlier calculations, has been used to capacity on higher priority projects.

A recently developed analytical description [3] of the amplitude and velocity of the shock wave produced in a target under end-on impact by a like-metal cylindrical projectile is summarized in this report. The analysis is then extended to provide the peak axial pressure generated at various depths in the target when the projectile and target materials are different. Detailed results are given for impact of aluminum, iron, lead, and copper into aluminum targets.

Finally, a summary of experimental data for impact of aluminum, steel, tungsten, and glass projectiles into aluminum targets is given and the results are discussed in terms of the theory.

SECTION II

CODES AND COMPUTER FACILITIES

In developing PICWICK II the same basic numerical scheme was used as in PICWICK I, but magnetic tapes are employed as external storage to permit a four-fold increase in the number of cells in the computational mesh. The code now permits approximately a 2000 cell mesh when using the full visco-plastic model. The code is presently operational in Fortran 2 as a Chain Job and in Fortran 4 as an Overlay. These two methods of sharing internal storage were employed so that repartitioning of the mesh could be accomplished with a minimum of the memory capacity of the IBM 7094. The repartitioning process allows a doubling of the linear dimensions of the cells in the computational mesh at desired stages of the cratering process to permit a greater volume of the target to be studied by the same number of cells. Thus the disturbance described by four cells at the instant prior to repartitioning is described by a single cell immediately subsequent.

The four-fold increase in the number of cells in the mesh provided by PICWICK II would normally mean a comparable increase in the computer time required for each cycle of the calculations. It has proved possible, however, to reduce the calculation time that would otherwise be required for an impact problem by about one-third. A Bypass subroutine has been incorporated which avoids making calculations in that part of the finite-difference mesh as yet undisturbed by the flow process. This device is especially effective in the early stages of the flow and after each repartitioning process.

Unfortunately computer time on the IBM 7094 at Eglin has not been available to utilize the new capabilities of the code. However, provisions have recently been made to use an alternate Air Force facility. More detailed studies of meteor bumper systems will be made. Impact by hollow cylindrical projectiles will also be treated.

SECTION III

REVIEW AND FORMULATION OF ANALYTICAL MODEL

In reference [3] it was shown that for end-on hypervelocity impact of a solid right-circular cylinder into a semi-infinite medium of like material the peak axial pressure in the target, its position and speed of propagation, can be determined accurately from an analytical model. This model assumes that the axial shock front, immediately after impact, moves with the constant impact shock speed RH until the point R1 is reached where the axial shock is first attenuated by rarefaction waves arising at impact at the projectile edge. This attenuation manifests itself by a rapid release of energy over a short axial distance, the effect approximating a line blast. At the very beginning of this period the shock front is planar and moving with the speed of a planar blast wave; however, the line blast effect diminishes the planar blast wave speed by an amount that is proportional to the speed of the cylindrically radial blast wave generated by it. As shown in more detail in reference [3] the pressure pulse moves into the target along the axial direction so that its position R, measured from the point of impact, satisfies the differential equation

$$\dot{R} = A \left[\frac{4k}{\sqrt{R-R_o}} - \frac{4k^2}{R-R_o} \right], \qquad (2)$$

where A, k, R_O are parameters of the motion and it is understood that (2) is valid for $R \ge R_1$. For $0 \le R \le R_1$, as mentioned above, we have $R = R_H$ where R_H is determined from the one-dimensional impact of two semi-infinite bodies, the corresponding impact interface pressure being denoted by p_H . The parameter k^2 has dimensions of a length and can be regarded as a measure of the average distance over which the line blast effect is operative. We shall find it more convenient, however, to non-dimensionalize this parameter and use instead the parameter

$$K = \frac{k}{\sqrt{L}}, \quad \overline{L} = (L^2 \ell)^{1/3} = L \left(\frac{\ell}{L}\right)^{1/3}$$
 (3)

where L, & are, respectively, the projectile radius and length.

The peak axial pressure profile can now be computed as a function of R from the following simultaneous set of three equations:

$$\frac{R}{\bar{L}} = \frac{R_o}{\bar{L}} + \left[\frac{2K}{1 - \sqrt{1 - \frac{\dot{R}}{A}}} \right]^2 \tag{4}$$

$$\dot{R} = \sqrt{\frac{p(x)}{\rho_0 (1-x)}} \tag{5}$$

$$p = p(x), x \equiv \rho_0/\rho$$
 (6)

where (4) is (2) in non-dimensional form and R_0/\overline{L} is given by

$$\frac{R_{o}}{\dot{L}} = \frac{R_{1}}{\dot{L}} - \left[\frac{2K}{1 - \sqrt{1 - \frac{\dot{R}_{H}}{A}}}\right]^{2} \tag{7}$$

Equation (5) is a combination of two of the Rankine-Hugoniot jump relations valid across the shock, while equation (6) is the Hugoniot equation of state of the target medium. The variable ρ is taken as the density behind the shock. The energy release point R_1 appearing in (7) is computed from the formula

$$R_1 = L\dot{R}_H / \left[c_H^2 - x_H^2 \dot{R}_H^2\right]^{1/2},$$
 (8)

where \mathbf{x}_H is the impact value of \mathbf{x} and \mathbf{c}_H is the impact value of the hydrodynamic sound speed, namely

$$c_{H}^{2} = -x_{H}^{2} \left[\left(\frac{dp}{dx} \right)_{x = x_{H}} \right] / \rho_{o} \qquad (9)$$

The pressure profile for $R \ge R_1$ is conveniently plotted by letting x be the running variable, taking it in the interval $xH \le x \le 1$. As x varies, R and p are determined and one then plots p vs R. The function p(x) is normally quite involved and does not permit an explicit determination of its inverse.

To use equations (4,5,6) one must know the parameter values A, K and R_0 . The parameter A is determined by requiring the peak axial pressure profile to have a point of inflection at $R=R_1$. In actuality it has a corner there; little is lost, however, if one approximates the physical process by a continuous curve with a continuous slope. This assumption leads to an explicit determination of A in the form

$$A = \dot{R}_{H} f(\beta), \qquad (10)$$

where

$$f(\beta) = \frac{51 - 44\beta + 8\beta^2 - 3\sqrt{33 - 8\beta}}{8(1 - \beta)(4 - \beta)},$$
 (11)

and β is in turn computed from the formulas

$$\beta = 4 d_{1} \left(1 - \frac{d_{1}}{d_{2}} \right)$$

$$d_{1} = p_{H} / (p_{H} + [1 - x_{H}] p'_{H})$$

$$d_{2} = 2 p'_{H} / (1 - x_{H}) p''_{H},$$
(12)

$$p_H' \equiv (dp/dx)_{x = x_H}$$
, etc.

As v ranges over all hypervelocities of interest, the dimensionless quantity β varies from -1 to 0. The quantity $f(\beta)$, however, exhibits variation only in the third decimal place, being approximately equal to 1.055.

The parameter R is known once K is available since by substituting the data $(R = R_1, R_H)$ into (4) we get relation (7).

The shock position R along the axis at time t since impact is obtained by solving the differential equation (2) and evaluating the constant of integration for conditions at the point R, . We find,

$$\frac{t}{\overline{L}} = \frac{R_1/\overline{L}}{\dot{R}_H} + \frac{1}{2AK} \left\{ \frac{1}{3} \left(\frac{R}{\overline{L}} - \frac{R_o}{\overline{L}} \right)^{3/2} + \frac{K}{2} \left(\frac{R}{\overline{L}} - \frac{R_o}{\overline{L}} \right) + K^2 \sqrt{\frac{R}{\overline{L}} - \frac{R_o}{\overline{L}}} + K^3 \ln \left(\sqrt{\frac{R}{\overline{L}} - \frac{R_o}{\overline{L}}} - K \right) \right\} .$$

$$- K^3 \left(\ln K + \frac{20}{3} \right) \right\} .$$
(13)

In determining the all-important parameter K use was made of the PIC WICK code solutions of the partial differential equations defining the hydrodynamic phase of the impact generated flow. In these solutions the projectile and target were of like material and the projectile shape was the standard one for which $L = \ell$. From a study of many such impact cases it was determined that K has the form

$$K = \alpha v_0^{-1/3} \quad , \tag{14}$$

where α is a parameter characterizing the target material. In all these cases where $L=\ell$, we note that \overline{L} is also equal to L. For differently shaped projectiles; i.e., for those where $L\neq \ell$, eq. (14) may still be valid provided the aspect ratio ℓ/L does not differ from unity by a factor greater than about three. To test this hypothesis the form (14) was used for a case of lead-lead impact at v=1 cm/ μ sec with L=1.8 cm and $\ell=3.6$ cm, the shape factor here being $\sqrt[6]{2}$. It was found that the (R,t) curve, using (13), matched the hydrodynamic code solutions for this case almost exactly (see Fig. 16 of [3]).*

^{*}If k were made dimensionless by dividing L instead of \overline{L} then the form factor $(\ell/L)^{1/6}$ would have to appear in the associated parameter K.

The manner in which K should be modified when projectile and target are not of identical material was given a preliminary investigation by considering impacts of aluminum projectiles of differing bulk densities into aluminum. PICWICK solutions were obtained for L = ℓ shaped projectiles at speeds v = 0.76 and 2.0 cm/ μ sec. A study of these solutions showed that the form of K given by (14) needed to be modified by a density factor, namely $1+0.15(1-\delta)$, where $\delta=\rho_{\rm D}/\rho_{\rm t}$ is the ratio of the projectile density to the target density. The corresponding profiles matched the PICWICK profiles remarkably well, even with δ as low as 1/6 (see the appropriate figures in reference 4). Since

$$1 + 0.15(1 - \delta) \doteq 1 + (\delta - 1)^{-1/6} \equiv \delta^{-1/6}$$

for δ close to 1, it is conjectured here that the appropriate density factor for the general case of dissimilar materials should be $\delta^{-1/6}$. The appropriate K would then be

$$K = \alpha v_0^{-1/3} \delta^{-1/6}$$
 (15)

The analytical model and the PICWICK computations jointly confirm that a thick target sees no essential difference between the like-metal impacts of geometrically similar projectiles of equal kinetic energies. This is amply demonstrated in Figures 1, 2. Figure 1, which appeared as Figure 10 of reference 3 , shows the peak axial pressure profiles generated by the impacts of two equi-energy aluminum projectiles into aluminum, one having dimensions ℓ = L = 0.26192 cm and speed v = 2.0 cm/ μ sec; the other, larger and slower, with speed v = 0.76 cm/ μ sec and dimensions $\ell' = L' = 0.49922$. The pressure curves have essentially coalesced into one at about 1.4 cm below the original target surface at a pressure of about 0.3 mb. There is, however, a difference in the times at which the pressure pulses for the two impacts pass a given axial location R. This is also shown in Figure 1, where it is seen that the pulse generated by the larger, slower projectile arrives at an axial location R some 0.35 psec later than the arrival of the pulse generated by the smaller faster projectile. This time lag was observed in the PICWICK data and was discussed in earlier reports 1,2.

Figure 2, taken from the work of reference 6, shows again the situation involving aluminum projectiles impacting aluminum; however, here we compare three projectile impacts, all at speed v = 2.0 cm/µsec, but involving projectiles of differing bulk densities (and hence, for equi-energy, of differing sizes). The projectiles are of normal density, density 1/3 normal and density 1/6 normal. Coalescense of the pressure profiles is obtained at a depth of approximately 0.8 cm below the target surface at a pressure of about 1 mb.

These dimensions were selected so that the cylinder would have a volume equal to the volume of a 3/32" sphere. In this report the gram-centimeter-microsecond system of units is used throughout.

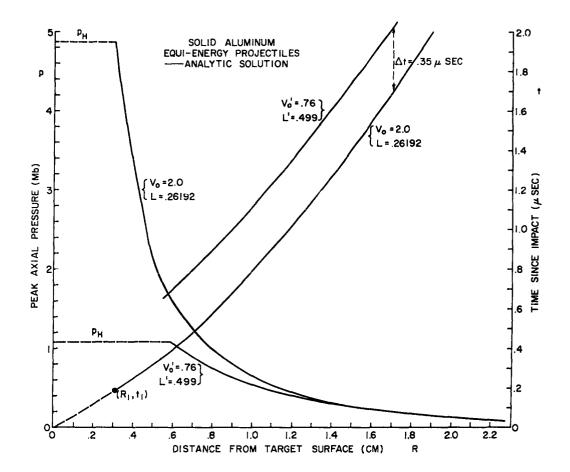


Figure 1. Comparison of shock waves produced in an aluminum target impacted by geometrically similar projectiles of aluminum. Analytic solutions are compared for impact velocities of .76 and 2.0 cm/usec.

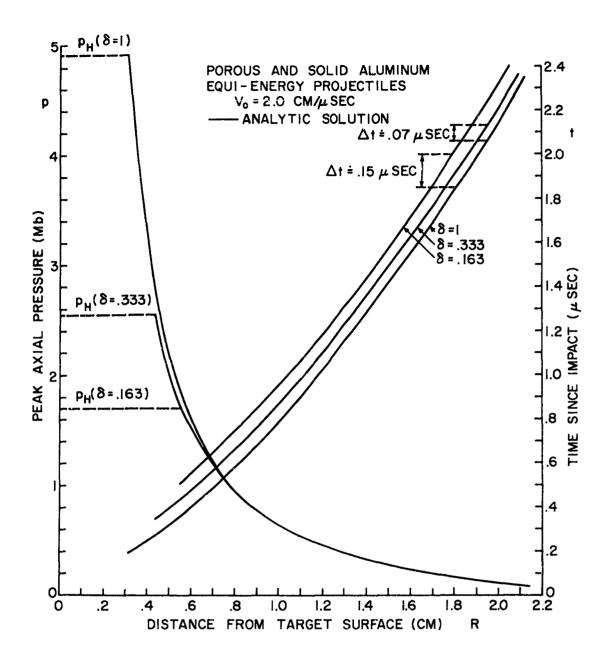


Figure 2. Comparison of shock waves produced in a solid aluminum target when impacted at 2.0 cm/ μ sec by normal and reduced density aluminum projectiles. Results depicted for L = ℓ = .26192 (δ = 1), L = ℓ = .3778 (δ = .333), and L = ℓ = .4797 (δ = .163).

SECTION IV

EXTENSION OF THE MODEL TO DISSIMILAR MATERIALS

When projectile and target are of dissimilar materials, the first step in determining the peak pressure profile is the evaluation of the necessary constants XH, RH, pH, A and R1. This is greatly facilitated by use of the simple computer program described in [3] for computing Hugoniot values at impact. Their values depend on the impact velocity, the equations of state of impacting materials, and the geometry of the projectile.

The principal question involved in extending the analytical model to dissimilar projectile and target materials is what one should use for K. PICWICK solutions are presently not available for helping to decide this directly; however, one can lean on those PICWICK solutions involving target and projectile of like material but where the projectile has reduced bulk density (an approximation to porosity). In effect, then, one extrapolates the form of K given by (15) to be applicable to any two dissimilar materials. This form can be rewritten in the following interesting fashion:

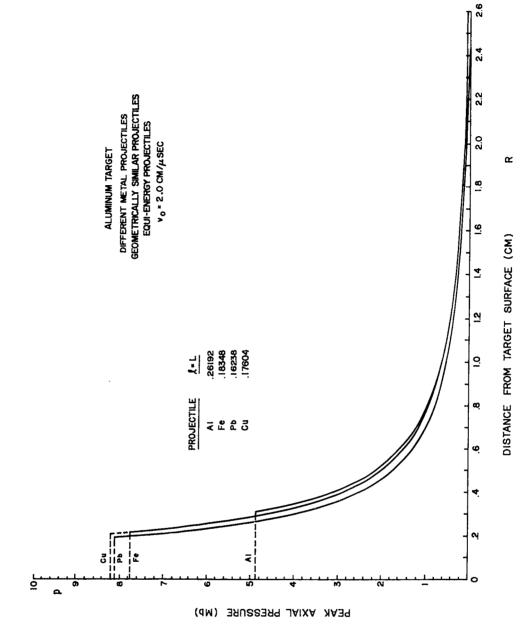
$$K = \frac{\alpha^*}{(E_p/M_t)^{1/6}},$$
 (16)

where E_p is the kinetic energy of the projectile and M_t is a mass of target material having the same volume as that of the projectile. α^* is merely $\alpha/\sqrt[3]{2}$ and so is again simply a numerical parameter characteristic of the target medium. Thus, K has a physical interpretation, being expressed in terms of the energy distribution produced in the target medium by the impacting projectile.

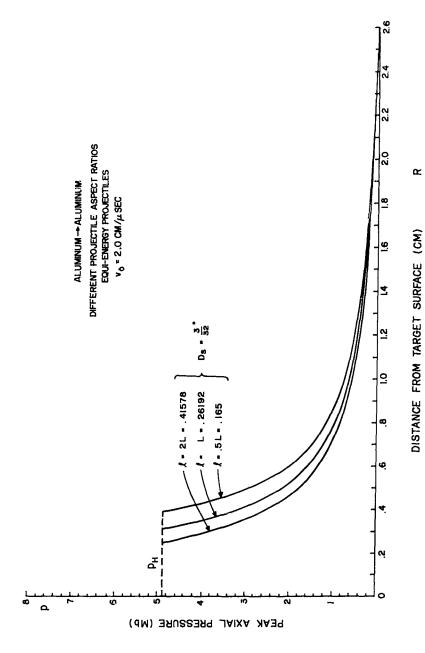
Computations were made using the analytical model and the extrapolated K given by (16) for impacts involving iron, copper, lead, and aluminum projectiles. The results are illustrated in Figures 3, 4, and 5.

In Figure 3, pressure profiles are shown for geometrically similar ($\ell=L$) equi-energy projectiles of iron, copper, lead, and aluminum impacting a thick aluminum target at $v_0=2.0$ cm/ μ sec. The aluminum projectile has L=0.26192 cm; the other projectiles then have dimensions in accordance with energy scaling. These are given on the figure. The coalescense of the profiles is quite remarkable for the iron and copper. The iron, copper, and aluminum profiles all coalesce for pressures below 0.8 mb. The lead profile, however, remains distinct even at pressures less than 0.2 mb.

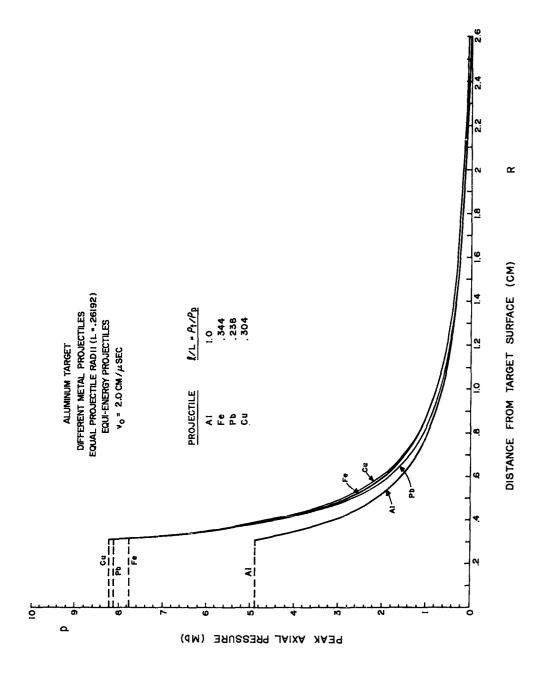
Figure 4 gives pressure profiles for three equi-energy aluminum projectiles at $v_0 = 2.0$ cm/ μ sec but with differing aspect ratios, namely $\ell/L = 2$, 1, and 1/2. Again the pressure profiles tend to converge and very nearly coalesce but at pressures less than 0.2 mb.



Peak pressures produced along the axis of an aluminum target impacted at $2.0~{\rm cm/\mu sec}$ by geometrically similar, equi-mass projectiles of indicated metal. Figure 3.



Peak pressures produced along the axis of an aluminum target impacted at 2.0 cm/ $\mu\,\rm sec$ by equi-mass cylindrical aluminum projectiles of indicated aspect ratios.. Figure 4.



Peak axial pressures in an aluminum target impacted at 2.0 cm/ μ sec by equi-mass cylindrical projectiles of indicated metals and aspect ratios. Figure 5.

Figure 5 shows the pressure profiles of iron, copper, lead and aluminum projectiles which are equi-energy (with $v_0=2.0~\text{cm/}\mu\text{sec}$) but not geometrically similar. Using the aluminum projectile with $L=\ell=0.26192$ cm as a standard the dimensions of the other projectiles p were computed from

$$\ell/L = \rho_{A1}/\rho_{p}$$
.

Thus, all the projectiles have the same radius but differing lengths. Again the profiles tend to converge but do not completely coalesce even at pressures less than 0.2 mb.

SECTION V

RELATION TO OTHER INVESTIGATIONS

The peak axial pressure profiles calculated by the foregoing theory serve as valuable supplementary information to detailed numerical calculations. A characteristic of numerical solutions obtained with finite difference schemes is an oscillation of computed pressures about the true value. This is especially true of particle-in-cell type calculations as a consequence of the discrete nature of the mass representation. Yet only the detailed numerical calculations describe the complete flow field behind the shock front. It is the momentum content of this total disturbance produced in the target that determines the final impact damage.

Detailed hydrodynamic calculation for unlike metal impact have been reported by Walsh, et al [5]. They concluded that in the hypervelocity regime the material of the impacting projectile did not significantly affect the flow produced in the targer. The projectile aspect ratio was also found to be insignificant provided it is within a factor of 3 of unity. These conclusions are actually incorporated into our extrapolations of the K in the analytical theory. The approximate merging of the pressure profiles depicted in Figures 3, 4, and 5 appear to be in general agree ment with these conclusions. The coalescence, however, is not as unambiguous as for the impacts by geometrically similar equi-energy projectiles of like materials at different velocities (Figures 1 and 12) or of geometrically similar projectiles of reduced bulk density (Figure 2).

Several experimenters have studied the penetration of projectiles of various materials into thick aluminum (2024-Al) targets. Figure 6 is a composite plot depicting the crater depth as a function of impact velocity for aluminum, steel, tungsten, and borosilicate glass projectiles. It is interesting to discuss the data in terms of the theoretical studies.

The data for the aluminum and steel projectiles are seen to extend to above their respective threshold velocities for energy scaling. The data appear to be meshing into the indicated hatched regions bounded by lines of slope = 2/3. Now, if the cratering process were indeed independent of the projectile material, the constant C appearing in the penetration formula (1) would depend only on the target material. Consequently, at a given impact velocity v > v, the following ratio would hold for the steel and aluminum projectiles impacting a target of given material,

$$\frac{(P_c/D_s)}{(P_c/D_s)_{A1 \to A1}} = \left(\frac{\rho_{Fe}}{\rho_{A1}}\right)^{1/3} = 1.43$$

The centers of the hatched regions in the plots actually satisfy a ratio closer to 2.

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VELOCITY (CM/μ SEC)

Figure 6. Experimental data depicting the depth of penetration at indicated impact velocity. This composite plot was made available by E. P. Bruce. Pc is the crater depth and Ds is the diameter of the projectile.

v_{°/C°}

.5

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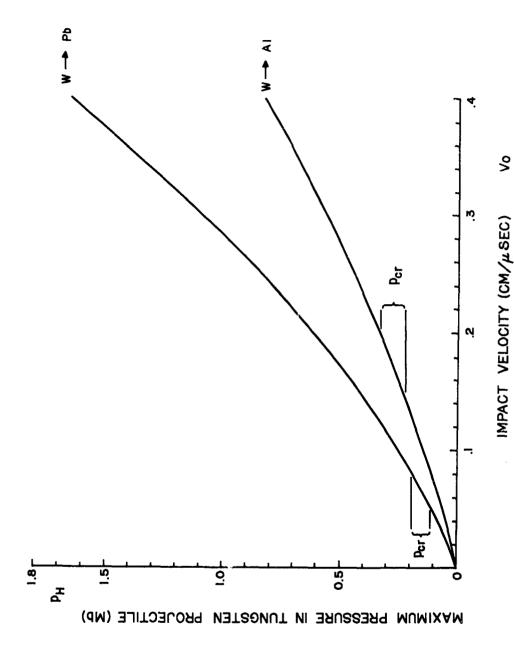
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With these experimental facts in mind, further detailed calculations should be made to determine the momentum content of the deformation wave produced in a target by equi-energy projectiles of material different from that of the target.

The velocities attained in the tests with tungsten projectiles are considerably below the sound velocity in aluminum; the data are below the threshold velocity for energy scaling. The penetration increases nearly linearly with increased velocity until $v = .125 \text{ cm}/\mu \text{ sec.}$ It then increases to a maximum before falling off slightly with increased velocity for velocities in the range .14 to .20 cm/ μ sec. A similar phenomenon was also observed in studies of impact of tungsten spheres into lead [12]. There the critical velocity range of .05 to .08 cm/usec, was found to be associated with the fragmentation of the brittle tungsten projectile. At higher velccities the crater became hemispherical and the penetration increased in accordance with v^{2/3} . In Figure 7, the maximum pressure produced in a tungsten projectile impacting both lead and aluminum targets is shown as a function of impact velocity. It is seen that for both target materials and the critical impact velocities produced a pressure of about .11 to .33 mb in the projectile. It is predicted that, as was the case with impact of tungsten into lead, as the velocity is increased well above the critical velocity associated with the projectile fragmentation penetration will increase according to $v_0^{2/3}$

The data for glass spheres impacting aluminum are especially interesting. The projectile is non-metallic and the data extend to much higher velocities, up to 1.2 cm/ μ sec. Even at the higher velocities, however, the penetration is increasing with increased velocity at a rate greater than $v^{2/3}$. The threshold velocity for energy scaling, $v^*>1.2$, is much higher than that required for the aluminum and steel projectile data. This is a result of the extremely small dimensions of the glass spheres, D=.005 cm as opposed to values of D=.3 to .6 cm for the bulk of the metal-metal data. The effect of size on v^* was predicted in an earlier report [2] on the basis of the visco-plastic model of the cratering process. As the velocity of the spheres is further increased the threshold velocity for energy scaling will be attained.



Maximum pressures produced in tungsten projectile impacting lead and aluminum targets at indicated velocities. Figure 7.

SECTION VI

CONCLUSIONS

An analytical method has been applied to determine the peak shock pressures experienced by dissimilar materials subjected to hypervelocity impact. The attenuation of the peak pressures with distance below the target surface is calculated for equi-mass aluminum, iron, copper, and lead projectiles impacting an aluminum target at $2.0~\mathrm{cm}/\mu\mathrm{sec}$. The computed pressure profiles tend to converge at the lower pressure but do not coalesce.

Available experimental data indicate that the proportionality constant C appearing in the penetration formula (1) depends upon the material of the impacting projectile. The mass and velocity of the projectile are apparently not the only considerations. An explanation of the dependence will be sought in terms of the impedance mismatch at the projectile-target interface. Moreover, detailed calculations using PICWICK II will be made for the case of unlike metal impact.

PICWICK II will also be used for detailed studies of meteor bumper systems and for impact by hollow cylindrical projectiles.

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